Mobile Robots

LD Series

Autonomous Intelligent Vehicles (AIVs), self-mapping, self-navigation.

- Natural-feature navigation
 Automatically plans routes to prevent collisions
- Fleet management
 Supervises and coordinates the entire fleet of up to 100 vehicles
- Easy deployment
 Short installation time: no facilities modifications





CE

Ordering Information

Mobile Robots-LD Platform

Appearance	Product Type	Product Name	Maximum Load	Maximum Speed		Configuration & Attachment*		
					Standard	-		37031-00000
					Docking Station kit		:12477-000 :12676-000L	37031-00002
ameon	OEM	LD-60	60 kg	1.8 m/s	Starter kit	Joystick MobilePlanner Software license Docking Station	:12944-000 :13558-000 :13495-200 :12477-000 :12676-000L	37031-10004
	OLIVI				Standard	-		37041-00000
					Docking Station kit	3	:12477-000 :12676-000L	37041-00002
		LD-90	90 kg	1.35 m/s	Starter kit	Joystick MobilePlanner Software license Docking Station	:12944-000 :13558-000 :13495-200 :12477-000 :12676-000L	37041-10004
	Cart	LD-105CT	105 kg	1.35 m/s	Standard		:13605-000 :13456-000	37141-00010
					Docking Station kit	Side Laser Docking Station	:13605-000 :13456-000 :12477-050 :12676-000L	37141-00012
					Starter kit	Side Laser Docking Station Battery Power Cable (0.45 m) Mobile Planner Software license Acuity Localization Joystick	:13605-000 :13456-000 :12477-050 :12676-000L :13495-200 :13700-000 :13558-000 :75020-000	37141-01014
			130 kg	0.9 m/s	Standard		:13605-000 :13456-000	37161-00010
		LD-130CT 130			Docking Station kit	Side Laser Docking Station	:13605-000 :13456-000 :12477-050 :12676-000L	37161-00012
					Starter kit	Side Laser Docking Station Battery Power Cable (0.45 m) Mobile Planner Software license Acuity Localization Joystick	:13605-000 :13456-000 :12477-050 :12676-000L :13495-200 :13700-000 :13558-000 :75020-000	37161-01014

^{*}Note: Battery 18578-000 must be ordered separately for a complete robot.

Software/Controller

Appearance	Product Name	Configuration & Attachment	Model
A Per	MobilePlanner	Installer (USB) * License dongle	13495-200
	Enterprise Manager 1100	License dongle	11167-100

^{* .}The latest version of MobilePlanner can be downloaded from Omron Adept Technologies Inc. website. http://www.adept.com/Robots-Mobile

Options

Appearance	Product Name	Specification	Configuration & Attachment	Model
		Single sensor	Sensor \times 1 , Mounting bracket \times 1, Power connector \times 1 , RS-232 connector \times 1 , 25 mm wide magnetic tape South top side. 50 m roll	13660-100
类	High Accuracy Positioning System	Double sensor	Sensor \times 2 , Mounting bracket \times 2, Power connector \times 1 , RS-232 connector \times 2 , 25 mm wide magnetic tape South top side. 50 m roll	13660-000
		Magnetic tape	25 mm wide magnetic tape South top side. 50 m roll	14925-000
	Acuity Localization	-	Camera, Mounting Kit, Cables, Leveling kit	13700-000
	Touchscreen	Bundle	Touchscreen with bracket, Power supply with bracket, Power Cable, from core to power supply (33 cm in length), Power Cable, from power supply to touchscreen (183 cm in length), Ethernet Cable, between touchscreen and core (153 cm in length), Gasket, between touchscreen and AIV mounting surface, Software package, including touchscreen support	13605-000
		Bundle	Laser × 2, Cable × 1 (Y Cable for 2 Laser)	13456-000
	Side Laser	Kit	Laser × 2, Cable × 1 (Y Cable for 2 Laser), Mounting kit × 2, Metal Cover × 2	13456-100
omnon o	Call/Door Box	WiFi Wired	Call/Door Box, Cable	13029-802

Accessories

Appearance	Product Name	Specification	Configuration & Attachment	Model
	Battery	Required	Must be ordered with each robot.	18578-000
Docking Sta		-	Docking Station, AC Power Cable	12477-000
	Docking Station	Extended Wall mount	Docking Station, AC Power Cable, Extended Wall mount (for Cart Transporter)	12477-050

LD Series

Appearance	Product Name	Specification	Configuration & Attachment	Model
	Joystick	Cable length: 0.6 to 3 m	-	13558-000
	Breakout Cable	-	DB44HD Breakout Cable (D-SUB44 pin Cable for Digital I/O interface)	14165-000
	Top Plate	Top cover for OEM type	-	12944-000
	Cart	-	-	75020-000
	Battery Power Cable	Cable length: 0.45 m	-	12676-000L

Specifications

Mobile Robots-LD Platform General Specifications

Item		OEM		Cart Transporter		Note
		37031-□□□□□	37041-□□□□□	37141-□□□□□	37161-□□□□□	Note
Materials KYDEX						
Dimension (L × W	′ × H)	699 × 500 × 383 mi	m	$894\times1074\times1394$	mm *	*. Height includes WiFi antenna.
Weight (with Battery)		62 kg		81 kg (Vehicle)/23 kg (Cart)		
	Ambient temperature	5 to 40 °C	5 to 40 °C			
	Ambient humidity	5 to 95 % (non-con	5 to 95 % (non-condensing)			
Environment	Operating Environment	Indoor usage only,	Indoor usage only, No excessive dust, no corrosive gas		Direct sunlight may cause safety laser false positive	
	IP rating	IP20				
	Cleanroom rating	Fed Class 100, ISC	Class5	None		

AIV (Autonomous Intelligent Vehicle) Specifications

	lk	0	EM	Cart Transporter		N. C.
	Item		37041-□□□□□	37141-□□□□□	37161-□□□□□	Note
	Floor Requirements	Level surface or co	oncrete (no water, no			
	Minimum floor flatness	F _F 25 (* ACI 117 st	andard)			* ACI 117 is the American Concrete Institute's standard for concrete floors. FF is flatness, FL is the level. Higher FF numbers represent flatter floors. FF25 is a fairly lenient specification.
Floor Conditions	Traversable step	15 mm max. * 1	10 mm max. * 1	5 mm max. * 2	5 mm max. * 2	*1. A speed of 250-300 mm/s and 250 mm/s, for the LD-60 and LD-90, is required for these steps. Faster or frequent driving over such steps or gaps will shorten the lifespan of the drivetrain components. Lower speeds may not traverse the step. Steps should have smooth, rounded
	Traversable gap	15 mm max.	15 mm max.	5 mm max. * 2	5 mm max. *2	profiles. *2. The Cart transporter with a cart is capable of driving over a gap or step of 5mm at a speed of 250 mm/s, but this should not be regarded as normal use. Regular driving over such gaps or steps will shorten the lifespan of the drivetrain components.
	Climb grade	Below 1: 12 (60 kg Flat floor only (ove		Flat floor only		
Navigation	Routing	Autonomous routin environment mapp	0,	Safety Scanning Laser based on		
	Environmental map making method	Scan by walking the Scan data in the M	e Mobile Robot thro obilePlanner.	ugh the environmen	t, and upload the	
Payload	Maximum Weight	60 kg	90 kg	105 kg *	130 kg *	*. Excluding cart weight

	ltom .	OI	EM	Cart Tra	nsporter	Note
	Item	37031-	37041-	37141-□□□□□	37161-	Note
	Maximum speed	1800 mm/s	1350 mm/s	1350 mm/s	900 mm/s	
Mobility	Maximum rotation speed	180°/s	180°/s	100°/s		
,	Stop position accuracy	± 100 mm: Position	ı ≯ , ± 2°:Rotation	*. ±10 mm: Position, ±0.5°: Rotation with option, (High Accuracy Positioning System)		
Drive wheel	Materials	Non-marking Nylor	foam-filled rubber,	non-conductive		
Drive wrieer	Size	200 dia. × 50mm n	ominal, 2 wheels			
Doggivo opetor	Materials	Conductive thermo	plastic rubber on Po	olyolefin		
Passive caster	Size	75 dia. × 41 mm no	minal, 4 casters			
	Battery	22-30 VDC				
	Capacity	72 Ah Battery cell i	nominal capacity			
	Run time	15 hours (continuo	us) approx.			With no payload condition
	Recharge Time	4 hours (5:1 ratio)	approx.			
	Battery Life cycles	2000 recharge cyc	es (Battery cell nom	ninal)		
Power	Charging method	Automatic / Manua	l			
	Auxiliary Power		witched Aux power witched Aux power vitched × 2 witched *			5, 12, 20, and 22-30 VDC power can be provided to external devices. *. 10 A Switched and 10 A Safe, Switched share the 10 A of current.
	Safety Standard	EN1525 / JIS D680	2 / ANSI B56.5			
Standard	Wireless	IEEE 802.11 a/b/g				
	Safety Scanning Laser	1 at front Class 1 PLd Safety per ISC Maximum range: 1 Field of view: 240°				
	Emergency Stop	1 at Operator panel 1 at HMI post touchscreen, 1 at Operator panel				
	Rear sonar	2 at rear, 2 m rang	9	Each pairs is one emitter and one receiver, working together		
	Front Bumper	1 at front of platform	n, 2pairs of sensors			
Safety Features	Low Front Laser	1 at front of platford Class 1 Maximum range: 4 Field of view: 270°				
	Side Laser	Option *		2 on horizontal tub Class 1 Maximum range: 4 Field of view: 270°		*. 2 on sides of payload structure, user-mounted
	Flash light	Light Disc in each side Light Disc in each side, Beacon on HMI post				
	Speaker	3.5", 80 W max.				
	Screen / Touch panel	3.5 in. TFT 320 × 2 color screen	40 pixels, 256 K	7.0 in. TFT LCD too RGB	uch panel , 18/24 bit	
Operator Interface	Button	ON Button: Green, OFF Button: Red, Brake-release buttr Keyswitch (Disable	on: Orange,	ON Button: Green, OFF Button: Red, Brake-release butt Keyswitch (Disable Latch Button, Unla	on: Orange, ed OFF Button),	
	Wireless	IEEE 802.11 a/b/g		1		
	Ethernet port		Maintenance LAN,	Auto-MDIX		
	Serial	RS-232 × 2, CAN E				
User I/F	Digital I/O	16 inputs, 16 output				
	Analog I/O		, 4 outputs (0-20 V)			
	Audio	. , ,	Audio In / Audio Out			
Cart Latching	Latching method	Not available	III / Mudio Out	Automatic		

LD Series

MobilePlanner	
Model	13495-200
Operating system	Windows 7 (32-bit/64 bit version) / Windows 8 (32-bit/64-bit version) / Windows 10 (32-bit/64-bit version)
CPU	1.5 GHz dual-core CPU recommended
Main memory	1.5 GB min. (4 GB min. recommended)
Hard disk	At least 200 MB of available space
Video memory	256 MB min.
Display	XGA 1024 × 768, 16 million colors
Communications ports	USB port (for license key)
Supported languages	Japanese, English

Enterprise Manager 1100

Enterprise manager 1100				
Model	11167-100			
Dimensions- W × D × H	426.0 × 438.4 × 42.4 mm			
Weight	6.8 kg			
Mounting method	1U rack mount in a standard 19-inch equipment rack			
Power Supply	100-240 VAC *			
Power Consumption	200W max.			
Operating Temperature	10 to 35 °C			
Storage Temperature	-25 to 60 °C			
Operating Humidity	8 to 90%, non-condensing			
Storage Humidity	5 to 95%, non-condensing			
Chassis protection class	IP20			
CPU	Intel® Xeon® CPU			
Main Memory	4 GB DDR3			
Storage	32 GB SSD			
Communication port	10/100/1000 Ethernet × 4, USB × 4, VGA			

*. typical 100 W

High Accuracy Positioning System

	ingit Accuracy i contoning System			
Model		13660-□00		
	Depth	30 mm		
	Width	160 mm		
Sensor	Rating	IP64		
	Environment	-40 to 85 °C		
	LEDs	Power, Tape present, Left marker, Right marker		
Magnetic Tone	Width	25 mm		
Magnetic Tape	Orientation	South up		
	Width	25 mm		
Markers	Length	300 mm min. for 500 mm/s drive speed		
(Magnetic Tape)	Orientation	North up		
	Separation from tape	15 - 30 mm		
Connections	Front sensor	RS232-1 (/dev/ttyUSB9) on the core		
	Rear sensor	RS232-2 (/dev/ttyUSB10) on the core		
	Power, both sensors	Aux Power, using the included splitter cable		

Acuity Localization

Model	13700-□00
Field of View	140°
Power Input	12 VDC (±10%) supplied from platform, through power connector
Power Consumption	3.3 W maximum

Touchscreen

Model	13605-000
Touch Panel	PCAP touch sensor, 5 simultaneous touches, black bordered cover lens
TFT Display	TFT LCD panel, 18/24 bit RGB parallel interface. 7.0 in. WVGA - Wide Viewing Angles, 5-Touch
Backlight	Constant current LED supply
Power Input	5 VDC supplied through power connector
Power Consumption	6.5 W maximum

Call/Door Box

Model	13029-802
Dimensions- W × D × H	141.4 × 74.7 × 30 mm
Weight	190 g
Mounting method	Mount to the provided wall frame with four screws
Power Supply	12 VDC
Power Consumption	0.5 A, 6 W typical
WiFi	IEEE 802.11 a/b/g/n
Communication port	Ethernet
1/0	Input x 2, Output x 2 (30 VDC, 2 A max)

Battery

Model	18578-000	
Run-time (no payload)	15 hours (continuous) approx.	
Weight	19 kg	
Voltage	22-30 VDC	
Capacity	72 Ah (Battery cell nominal)	
Recharge time	4 hours, approx.	
Life time	2000 times 80% DOD (Battery cell nominal), 7 years, approx., 16 hrs/day, 5 days/wk 4 years, approx., 19/7 (full-time)	

Docking Station

Model	12477-0□0
Current	8 A *1
Contacts	2
Power	100 to 240 VAC, 50 to 60 Hz
Power consumption	800 W
Humidity	5 to 95 % non-condensing
Temperature	5 to 40 °C
Dimensions- W \times D \times H	349 × 369 × 315 mm (495 × 495.5 × 317 mm) *2
Weight	8.2 kg
Mounting	Wall bracket, directly to floor, or on floor with floor plate
Indicators	Power on - blue Charging - yellow
Connector	For out-of-platform battery charging
*1. Thermal fuse in AC power	switch (10 A Time-lag fuse at switch for legacy

^{*1.} Thermal fuse in AC power switch (10 A Time-lag fuse at switch for legacy dock)*2. () for with Floor plate

Joystick

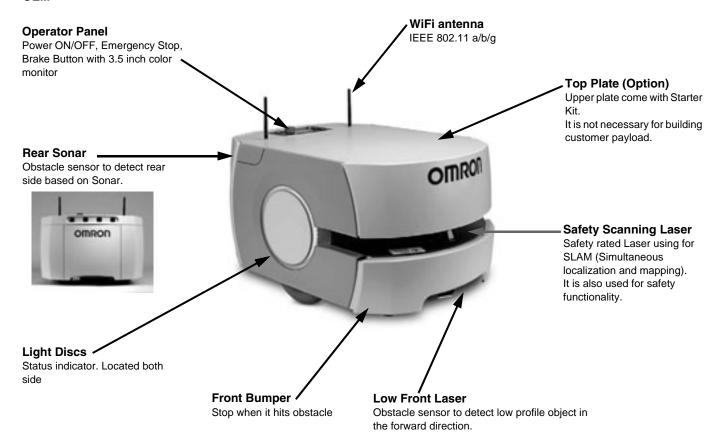
Model	13558-000
Weight	550 g
IP rating	IP56

Cart

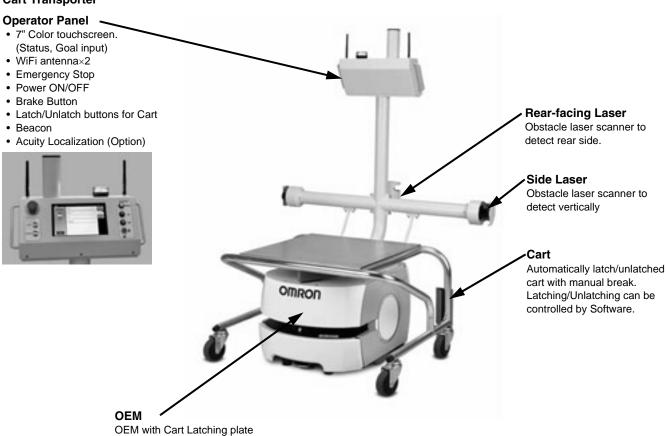
Model	75020-000
Dimension (L \times W \times H)	592 × 846 × 480 mm
Weight	23 kg
Rating	ESP rated
Passive Casters	2 front, 2 rear, spring-loaded
Caster diameter	100 mm nominal
Caster Brakes	at 2 rear casters

Components and Functions

OEM



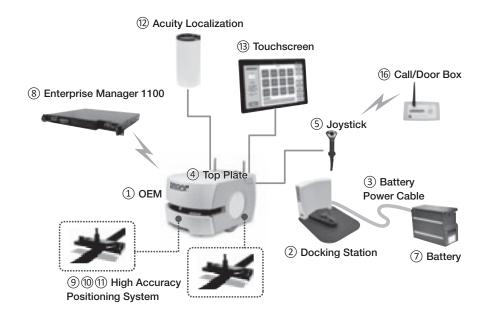
Cart Transporter



LD Series

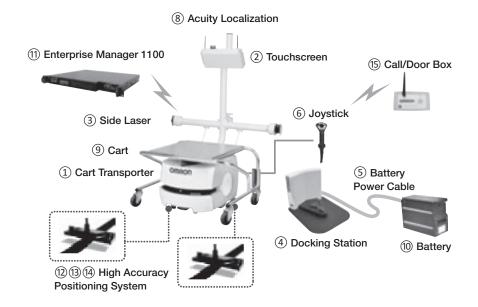
System Configuration

OEM



	Product Name	Model	Description	Docking Station kit/Starter kit
1	OEM	370□1-00000	A Mobile Robot OEM. The Battery is not included.	Included in Docking Station kit and Starter kit
2	Docking Station	12477-000	A docking station to charge the Battery installed in the Mobile Robot.	Included in Docking Station
3	Battery Power Cable	12676-000L	A cable to connect a Battery and Docking Station to charge the Battery outside of the Mobile Robot.	kit
4	Top Plate	12944-000	A upper plate of the Mobile Robot OEM. It is not necessary for building customer payload.	
(5)	Joystick	13558-000	Used for manually controlling the Mobile Robot.	Included in Starter kit
6	MobilePlanner	13495-200	PC software to configure, drive and observe the Mobile Robot, including a USB license dongle.	
7	Battery	18578-000	A Battery that is installed in the Mobile Robot.	-
8	Enterprise Manager 1100	11167-100	A system that manages a fleet of Mobile Robots, including a network appliance, software, and a USB license dongle.	-
9	High Accuracy Positioning System (Single sensor)	13660-100	A sensor and magnetic tape to achieve accurate alignment when the Mobile Robot follows driving forward. The sensor is attached to the Mobile Robot.	-
10	High Accuracy Positioning System (Double sensor)	13660-000	Two sensors and magnetic tape to achieve accurate alignment when the Mobile Robot follows driving both forward and backward. The sensors are attached to the Mobile Robot.	-
11)	Magnetic tape	14925-000	Magnetic tape for the High Accuracy Positioning System. The tape is applied to signal the Mobile Robot where to stop.	-
12	Acuity Localization	13700-000	Used where process layout or obstacle location changes often. Installed on a payload structure attached to the Mobile Robot.	-
13	Touchscreen	13605-000	Allows operators to check the status of the Mobile Robot, enter goals, and pause the Mobile Robot. Installed on a payload structure attached to the Mobile Robot.	-
14)	Side Laser Bundle	13456-000	Used to detect obstacles that are at heights the safety scanning laser of the Mobile Robot cannot detect. Installed on a payload structure attached to the Mobile Robot.	-
15)	Side Laser Kit	13456-100	Includes the above mentioned Side Laser, mounting kit, and metal covers to protect from lasers.	-
16	Call/Door Box	13029-802	Used to issue a request for a Mobile Robot to go to the goal or to open a closed door. Installed at the goal or door to open.	-
17)	Breakout Cable	14165-000	A D-SUB44 pin cable for digital I/O interface of the Mobile Robot.	-

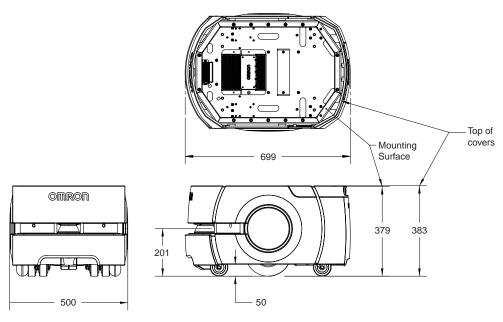
Cart Transporter



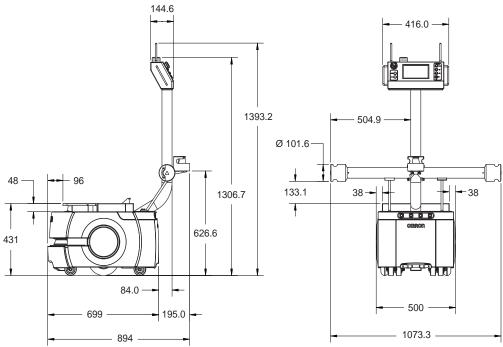
	Product Name	Model	Description	Docking Station kit/Starter kit
1	Cart Transporter	371□1-00000	A Mobile Robot Cart Transporter. The Battery is not included.	
2	Touchscreen	13605-000	Allows operators to check the status of the Mobile Robot, enter goals, and pause the Mobile Robot. Installed on a payload structure attached to the Mobile Robot.	Included in Docking Station kit and Starter kit
3	Side Laser	13456-000	Used to detect obstacles that are at heights the safety scanning laser of the Mobile Robot cannot detect. Installed on a payload structure attached to the Mobile Robot.	
4	Docking Station	12477-000	A docking station to charge the Battery installed in the Mobile Robot.	Included in Docking Station
(5)	Battery Power Cable	12676-000L	A cable to connect a Battery and Docking Station to charge the Battery outside of the Mobile Robot.	kit
6	Joystick	13558-000	Used for manually controlling the Mobile Robot.	
7	MobilePlanner	13495-200	PC software to configure, drive and observe the Mobile Robot, including a USB license dongle.	Included in Starter kit
8	Acuity Localization	13700-000	Used where process layout or obstacle location changes often. Installed on a payload structure attached to the Mobile Robot.	
9	Cart	75020-000	A cart designed for Mobile Robot Cart Transporter.	
10	Battery	18578-000	A Battery that is installed in the Mobile Robot.	-
11)	Enterprise Manager 1100	11167-100	A system that manages a fleet of Mobile Robots, including a network appliance, software, and a USB license dongle.	-
12	High Accuracy Positioning System (Single sensor)	13660-100	A sensor and magnetic tape to achieve accurate alignment when the Mobile Robot follows driving forward. The sensors are attached to the Mobile Robot.	-
(13)	High Accuracy Positioning System (Double sensor)	13660-000	Two sensors and magnetic tape to achieve accurate alignment when the Mobile Robot follows driving both forward and backward. The sensors are attached to the Mobile Robot.	-
14)	Magnetic tape	14925-000	Magnetic tape for the High Accuracy Positioning System. The tape is applied to signal the Mobile Robot where to stop.	-
15)	Call/Door Box	13029-802	Used to issue a request for a Mobile Robot to go to the goal or to open a closed door. Installed at the goal or door to open.	-
16	Breakout Cable	14165-000	A D-SUB44 pin cable for digital I/O interface of the Mobile Robot.	-

(Unit: mm)

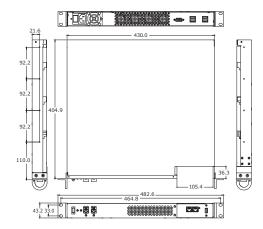
Mobile Robots-LD Platform OEM



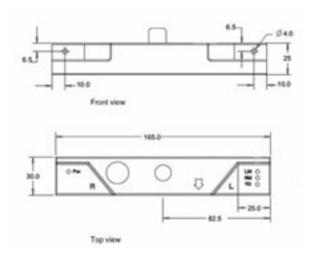
Cart Transporter



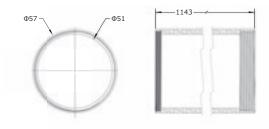
Enterprise Manager 1100



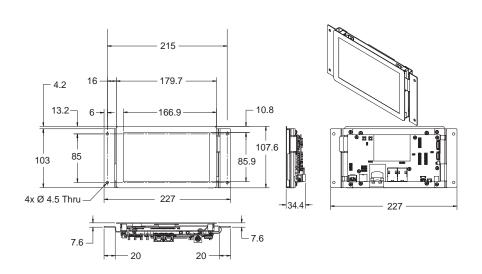
High Accuracy Positioning System



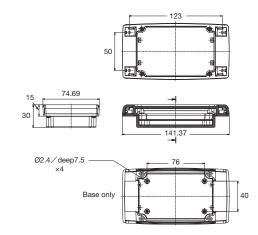
Acuity Localization



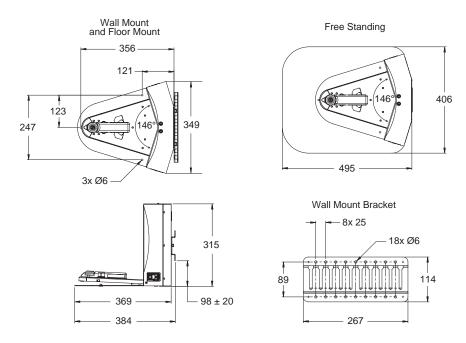
Touchscreen



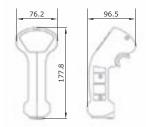
Call/Door Box



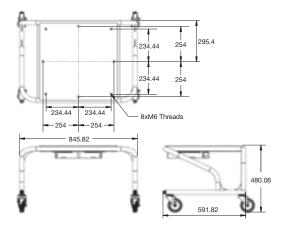
Docking Station



Joystick



Cart



Related Manuals

Manual No.	English title	
I611	Mobile Robots LD Platform User's Guide	
l612	Mobile Robots LD Cart Transporter User's Guide	
I613	Mobile Robots LD Platform Peripherals Guide	
I614	Mobile Robots Software Suite User's Guide	
I615	Enterprise Manager 1100 User's Guide	
I616	Mobile Robot Safety Guide	
I617	Advanced Robotics Command Language Reference Guide	
I618	Advanced Robotics Command Language Enterprise Manager Integration Guide	

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